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TAKE-OUT ROBOT

MBW-170

256
Packaging motion Max. 256 points

115 × 2
Free packaging motion 115points × 2stage

Forward and rotate at removing side

Posture control during traverse

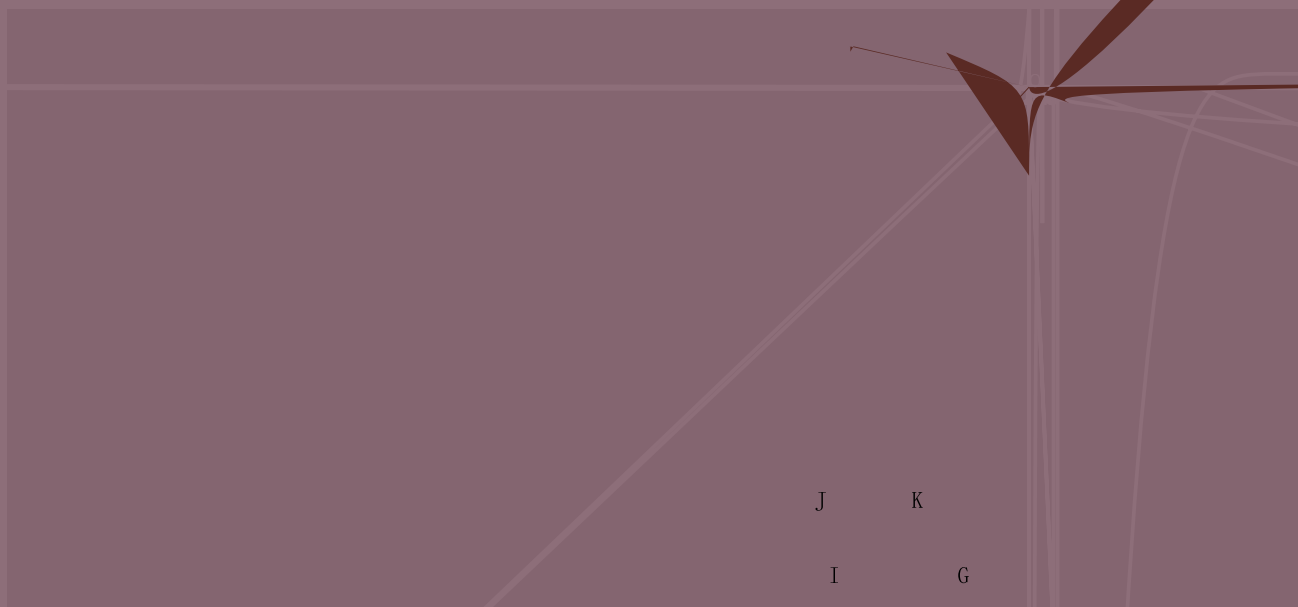
Posture midway descent at release side

Ejector link

2

100

2



外形尺寸 OUTER DIMENSIONS

MBW-170

OPTION FUNCTION

A	Overall height	2320(2440)mm
B	Overall length	3700(4180)mm
C	Transverse stroke	2500(3000)mm
D	Main- arm vertical stroke	1700(2000)mm
E	Main- arm vertical standby	350mm
F	Bottom of crosswise to chuck mount position	- - -
G	- Base side face- Box end	710mm
H	Sub- arm Vertical standby	- - -
I	Main- arm reach max	1875mm
J	Main- arm crosswise stroke max	1600mm
K	Main- arm crosswise standby min	275mm
L	Main/Sub- arm proximity min	- - -
M	Sub- arm crosswise stroke max	- - -
N	Sub- arm crosswise standby min	- - -
O	- Crosswise arm end- Box end	2475mm

Air nipper in chuck circuit
 NT -
 NT gate cutting on crossmember of moving
 4
 Additional vacuum sensing unit 4 circuits
 4
 Product gripping 4 circuits
 Mold close during ascend
 Rotation unit
 Ejector return unit
 12
 EUROMAP 12
 67
 EUROMAP 67

- 当尺寸C是2500mm时，尺寸B为3700mm
- when dimension C is 2500mm , B is 3700mm

- 当尺寸C是3000mm时，尺寸B为4180mm
- when dimension C is 3000mm , B is 4180mm

- 当尺寸D是1700mm时，尺寸A为2320mm
- when dimension D is 1700mm , A is 2320mm

- 当尺寸D是2000mm时，尺寸A为2440mm
- when dimension D is 2000mm , A is 2440mm

Feature and scope of the product does not guarantee the product attributes, only for reference. Our scope of delivery and services provided are based solely on the terms of delivery and services provided are based solely on the terms of the contract. Technical data and illustration are only for reference. We reserve the rights of changing.

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2

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